


UML for embedded software (II)

課程：嵌入式系統與軟體工程

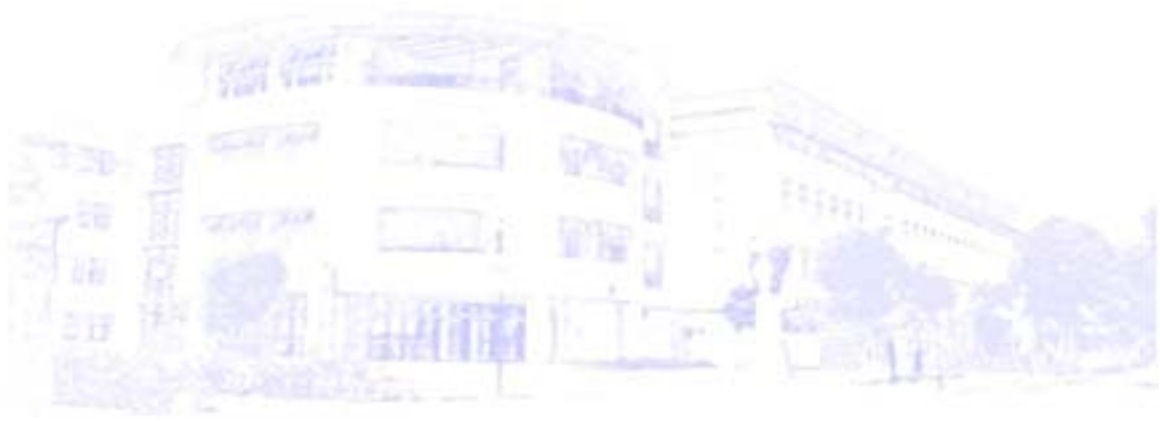
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ESW聯盟 「嵌入式系統與軟體工程」

How to Describe Behavior?



Behavior Modeling

- An Introduction to Behavior Modeling
- Sequence Diagrams
- Collaboration Diagrams (UML 2.0: Communication Diagrams)
- Statechart Diagrams
- Activity Diagrams

An Introduction to Behavior Modeling

- All systems have a *static structure* (documented by class diagrams) and *dynamic behavior* (documented by dynamic diagrams).
- Dynamic behavior is described by:
 - **Sequence Diagrams**: describe how objects interact and communicate with each other, focusing on time sequence;
 - **Collaboration Diagrams**^(*): describe how objects interact, focusing on space;
 - **Statechart Diagrams**^(**): describe which states an object can have during its life cycle, and the behavior in those states; and
 - **Activity Diagrams**: show objects that perform work in terms of activities.

UML 2.0: (*) Communication diagrams; (**) State machine diagrams.

Introduction to Behavior Modeling (cont'd)

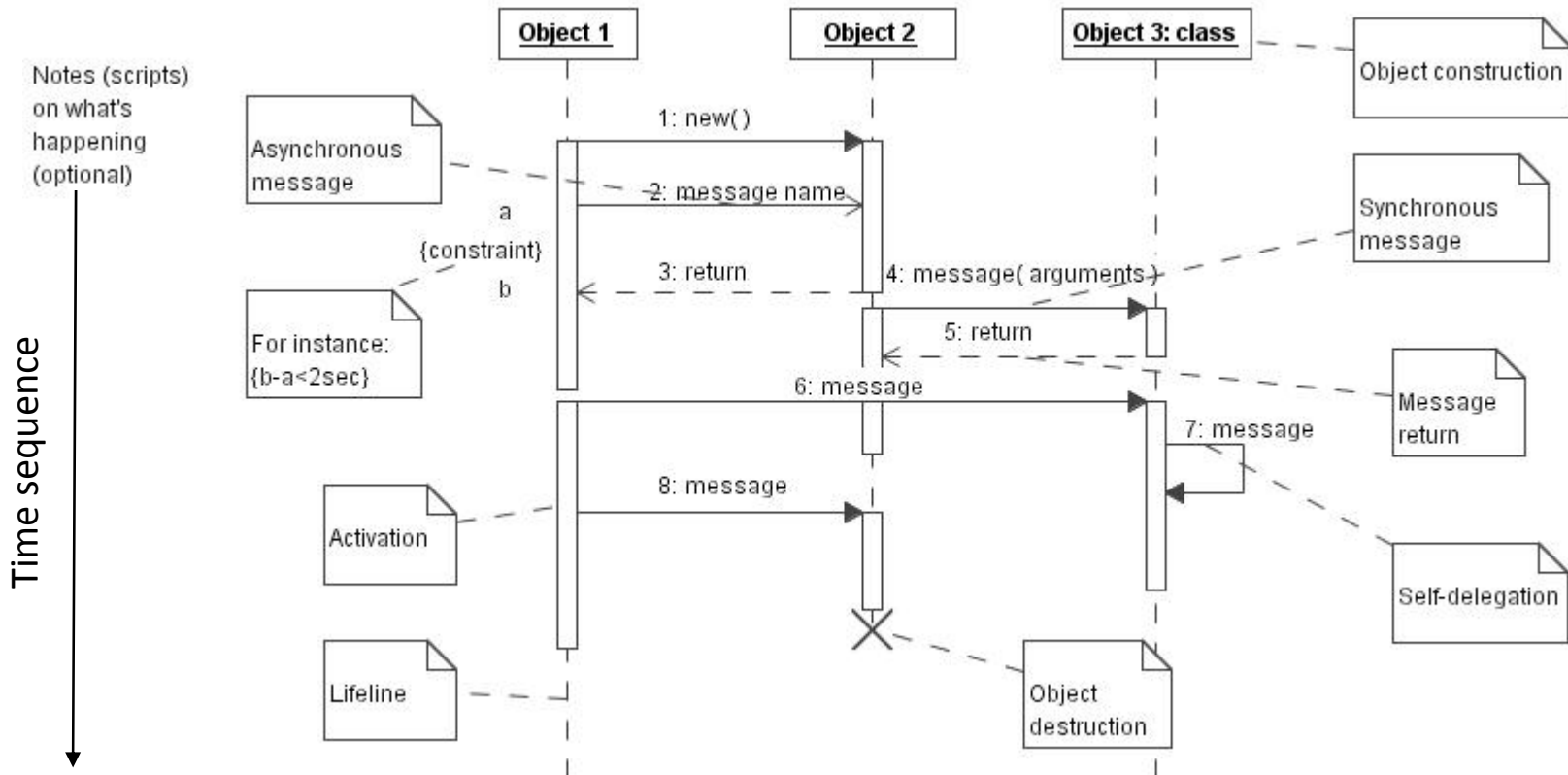
- **Interaction Diagrams** are used when modeling the dynamic aspects of a system. There are two way to use interaction diagrams [Booch et al. 1999]:
 - To model flows of control by time ordering
 - Sequence diagrams are used
 - To model flows of control by organization
 - Collaboration diagrams are used.

Sequence Diagrams

- A **Sequence Diagram** shows the chronological order of objects interactions.
 - The objects (not classes) and the messages that pass between them when an interaction occur.
 - Messages show one object interacting with another.
 - Two specific features of a sequence diagram:
 - **Object lifeline**: represents the existence of an object over a period of time, that is, objects may be created or destroyed during the interaction.
 - **Focus of control**: shows which object is currently active, that is, the activations of the objects.
 - Using sequence diagrams
 - To map functionality stipulated by use cases into classes
 - To help determine what classes to reuse, enhance
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Sequence Diagrams (cont'd)

- Notations to create a sequence diagram.

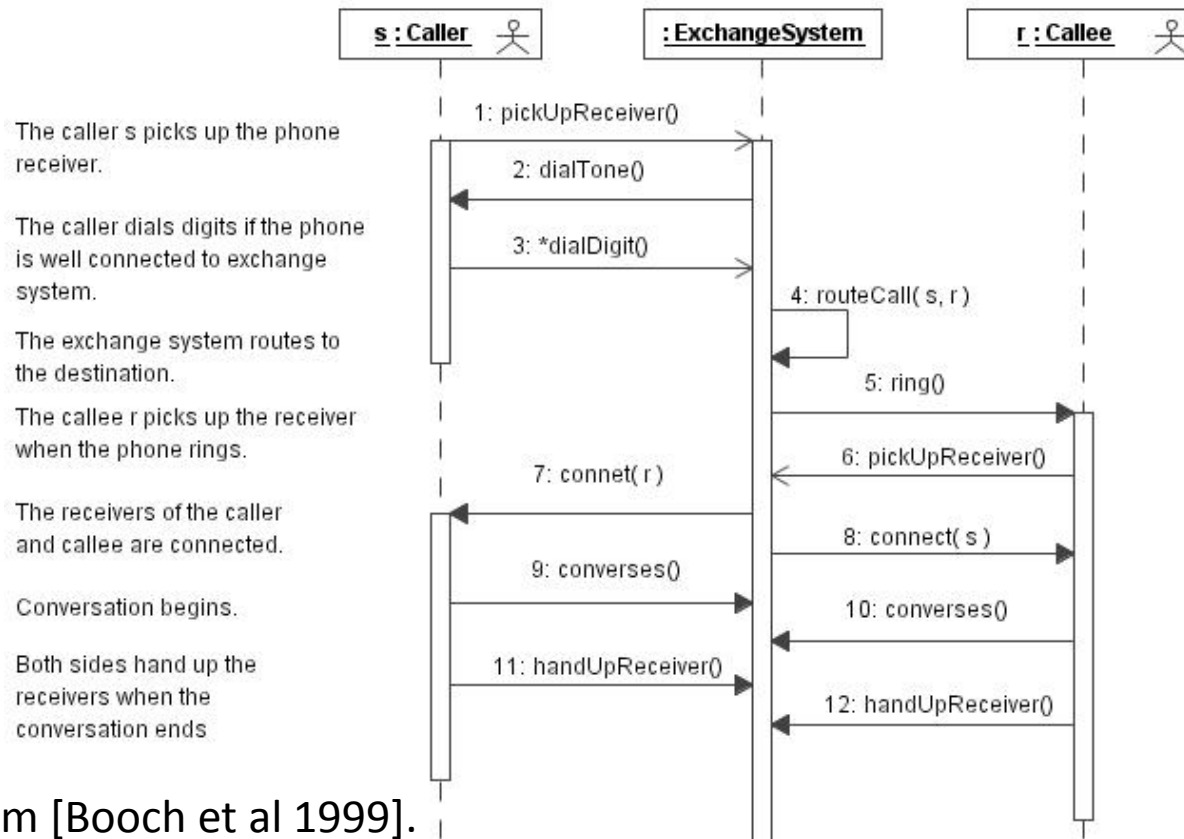


Sequence Diagrams (cont'd)

- Message names:
 - **Synchronous message**: the sender sends the message and waits for the receiver to return from the executing the message.
 - **Asynchronous message**: the sender sends the message and continually executes it, not waits for a return from the sender.
 - **Message return**: the receiver of the message returns activation of the sender's message.
 - **Object destruction**: The sender destroys the receiver.
 - **Activation (or focus of control)**: When a lifeline is executing a message.
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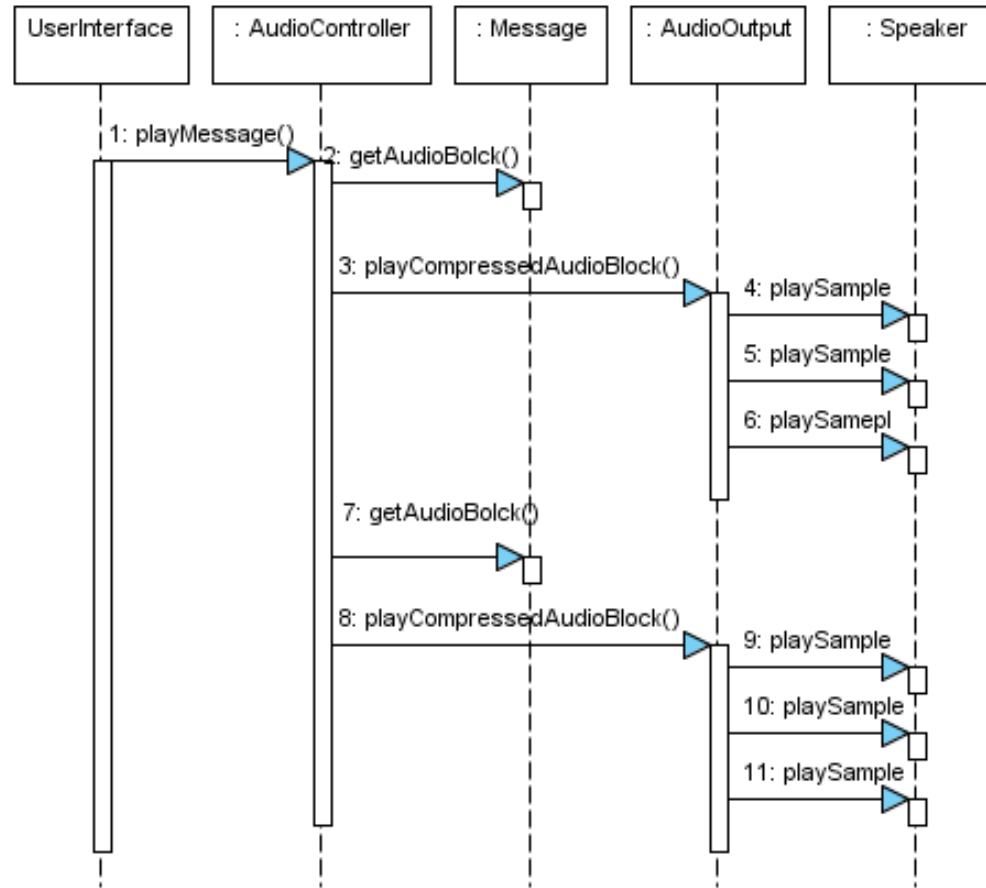
Sequence Diagrams (cont'd)

- Example: A simple sequence diagram of Phone Call(*).



(*) Adapted from [Booch et al 1999].

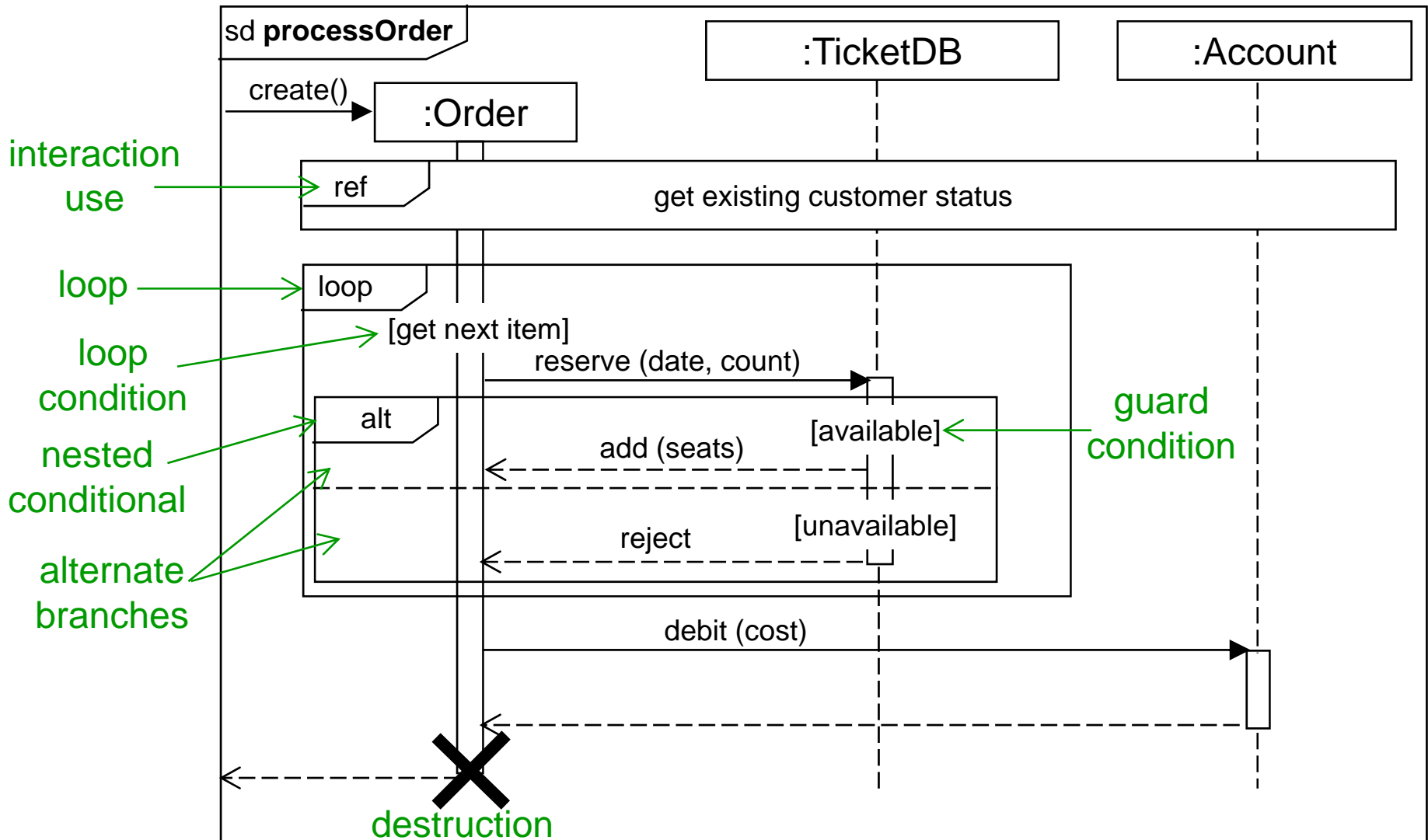
Audio Output to Speaker



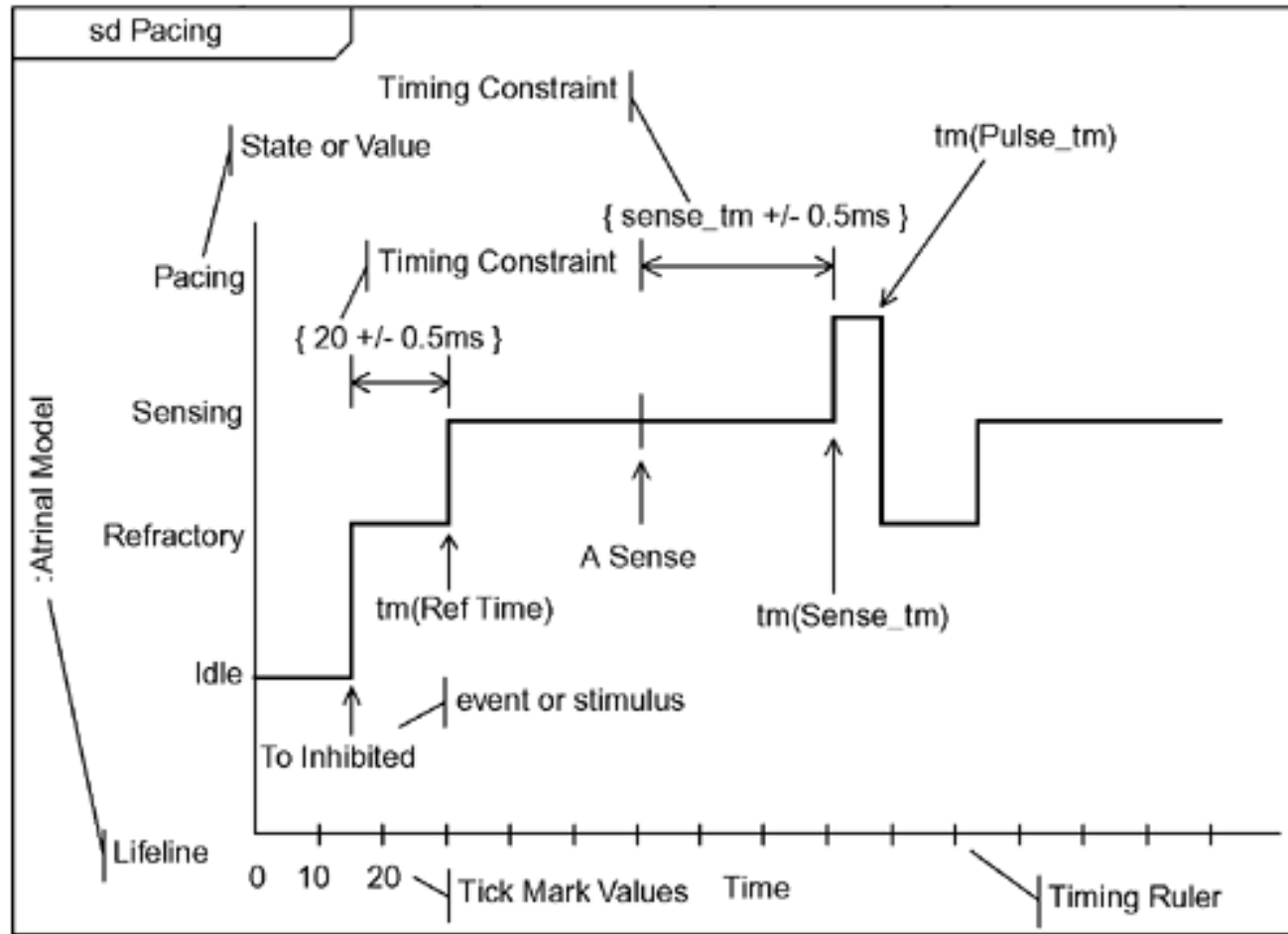
Decomposing Sequence Diagrams

- Sequence diagrams suffer from scalability problems when there are any
 - Lifelines
 - Messages
- UML 2 provides the ability to decompose sequence diagrams both vertically and horizontally
 - Lifelines may be decomposed into interactions (separate sequence diagrams)
 - Interaction fragments may be referenced on another diagram

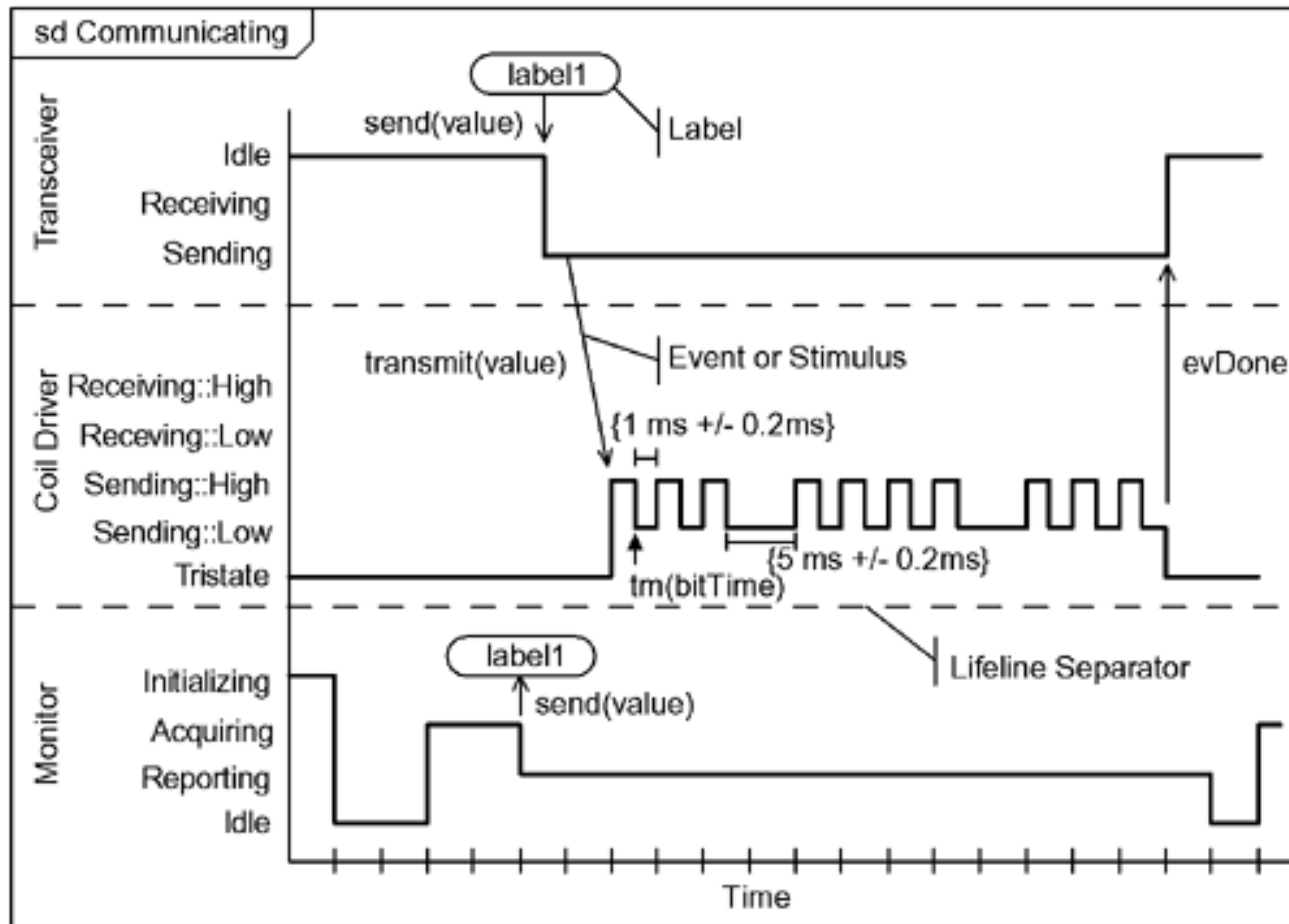
SEQUENCE DIAGRAMS



UML 2.0 Timing Diagrams



UML 2.0 Timing Diagrams

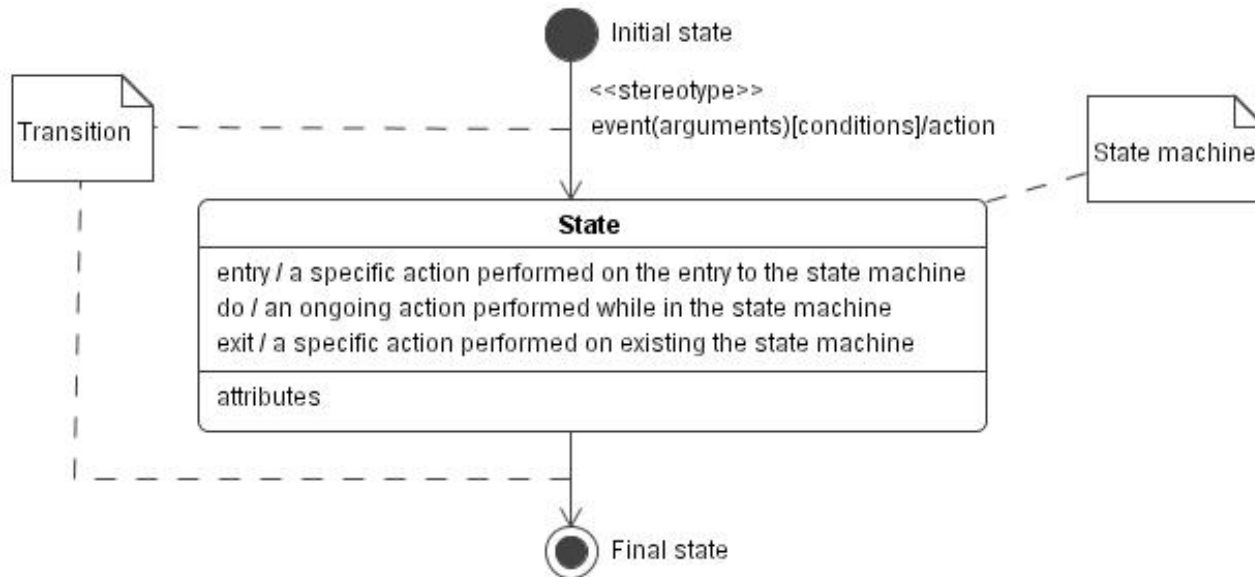


State Machine Diagrams

- A **State machine Diagram** shows a structured finite state machine that expresses an object lifecycle, that comprises:
 - **State**: represents a situation during the life of an object;
 - **Event**: represents an incident or indications that progression is happening;
 - **Transition**: specifies what new state is achieved under transition rule when an object receives a particular event;
 - **Action**: an executable atomic computation that results in a transition from one state and another, and cannot be interrupted.
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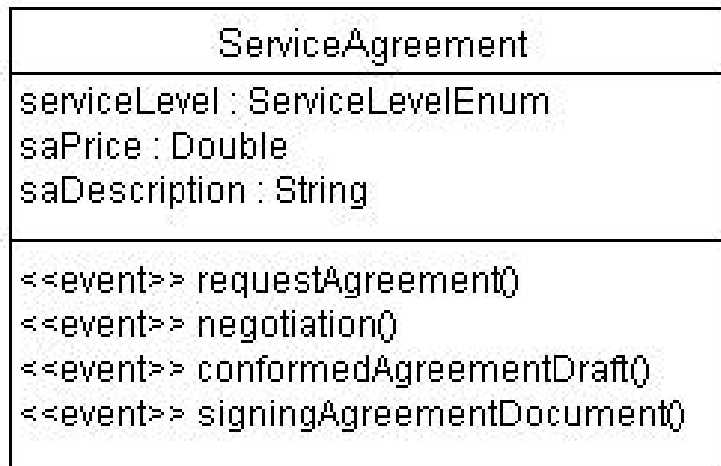
Statechart Diagrams (cont'd)

- A **State Machine** specifies the sequences of states during the lifetime of an object in response to events, together with its response to those events.
 - A state machine: state, transition, initial state, final state



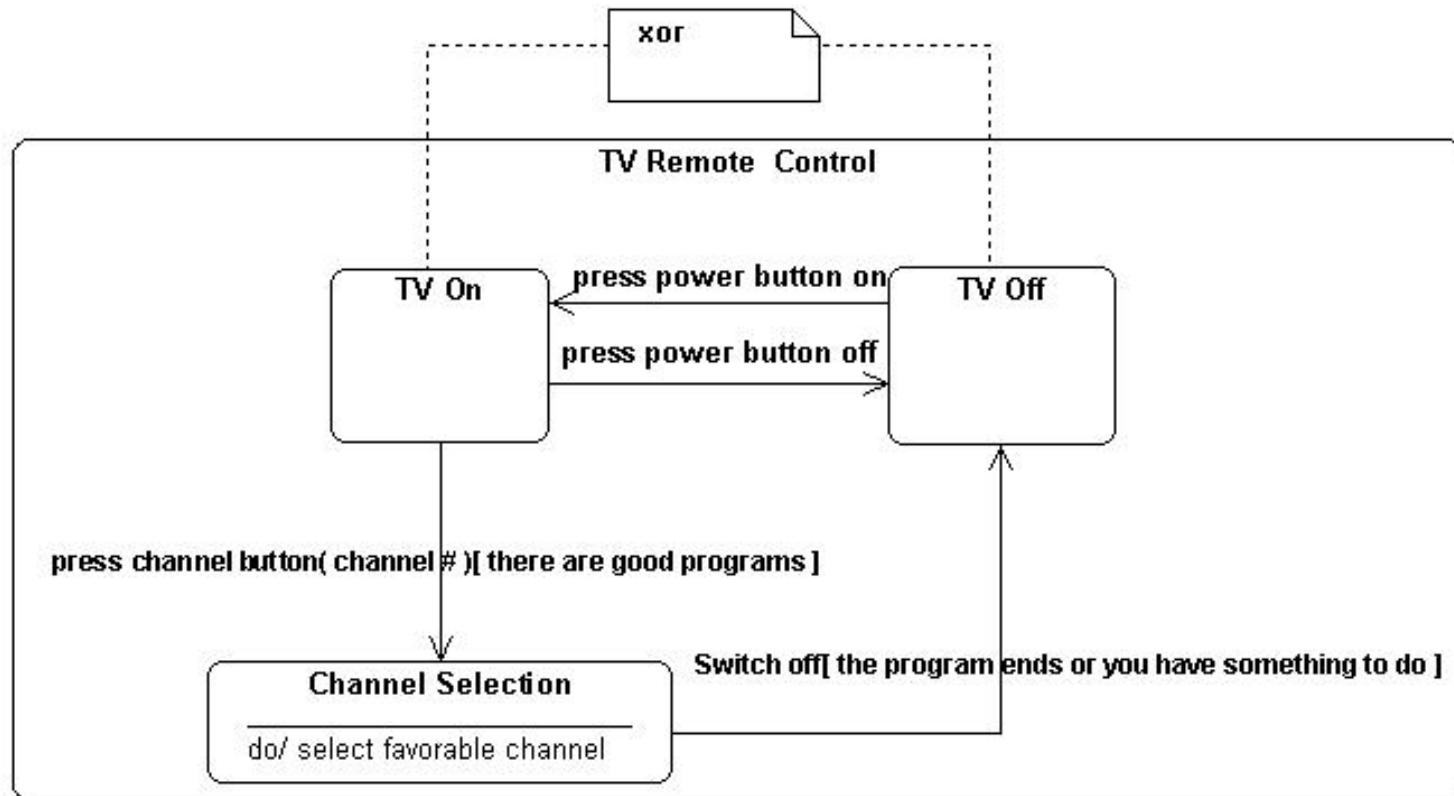
Statechart Diagrams (cont'd)

- One state machine for each class (a class may be seen as a state machine). For example:



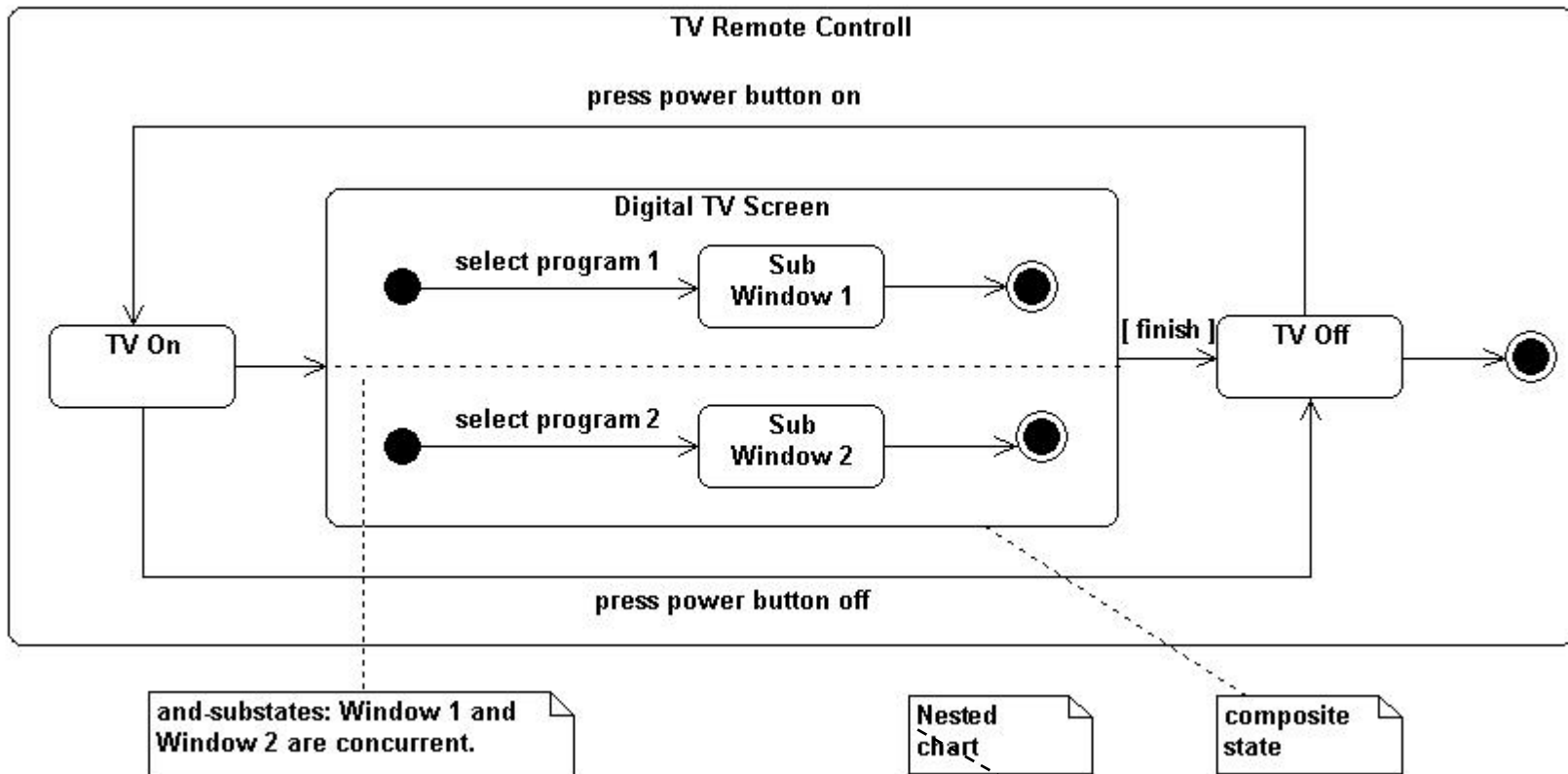
Statechart Diagrams (cont'd)

- Generalization: or (xor) substates



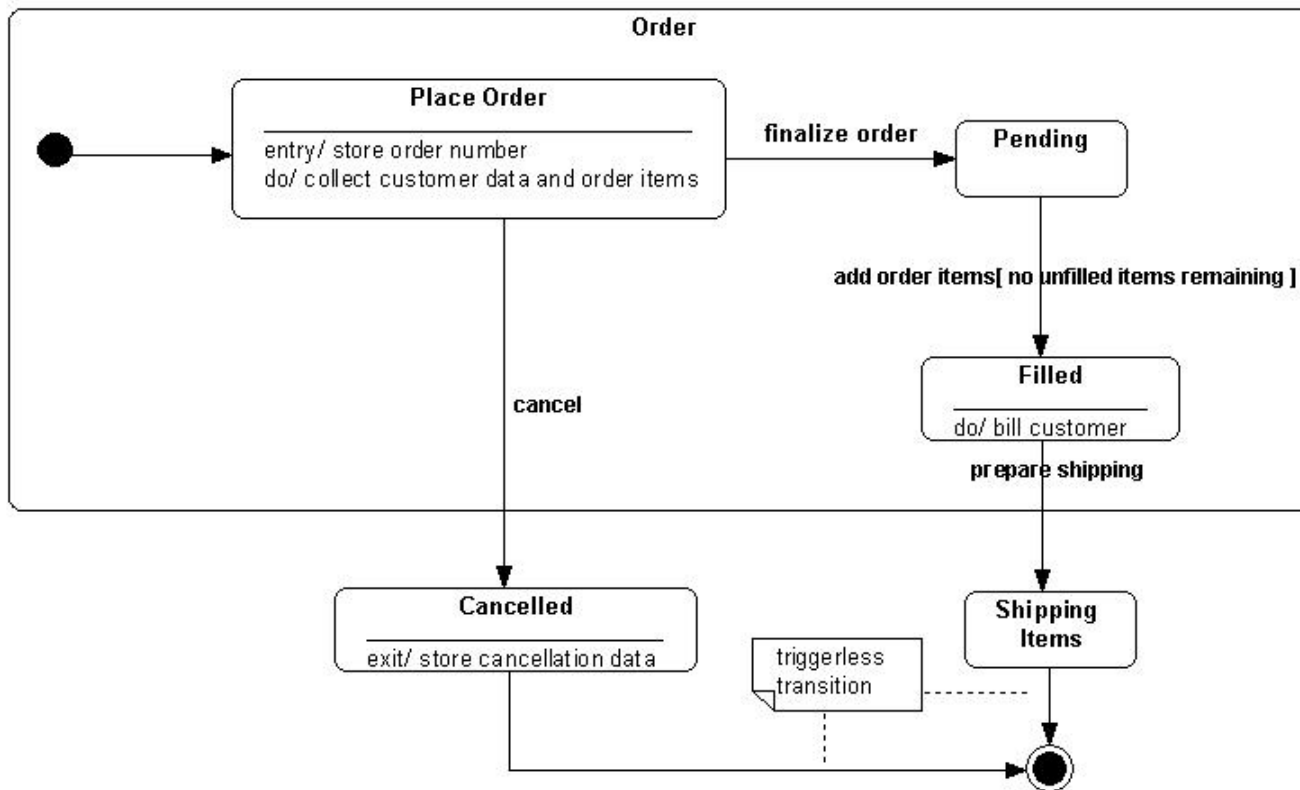
Statechart Diagrams (cont'd)

- Aggregation: and-substates (concurrent substates)



Statechart Diagrams (cont'd)

- Example: Order class



Types of Events

- UML defines 4 kinds of events
 - **Signal Event**
 - Asynchronous signal received e.g. evStart
 - **Call Event**
 - operation call received e.g. opCall(a,b,c)
 - **Change Event**
 - change in value occurred
 - **Time Event**
 - Absolute time arrived
 - Relative time elapsed e.g. tm(PulseWidthTime)

Handling Transitions

- If an object is in a state S that responds to a named event evX , then it will act upon that event
- It will transition to the specified state, if the event triggers a named transition and the guard (if any) on that transition evaluates to TRUE. It will execute any actions associated with that transition
- Handle the event without changing state if the event triggers a named reaction and execute all the list of actions associated with that reaction

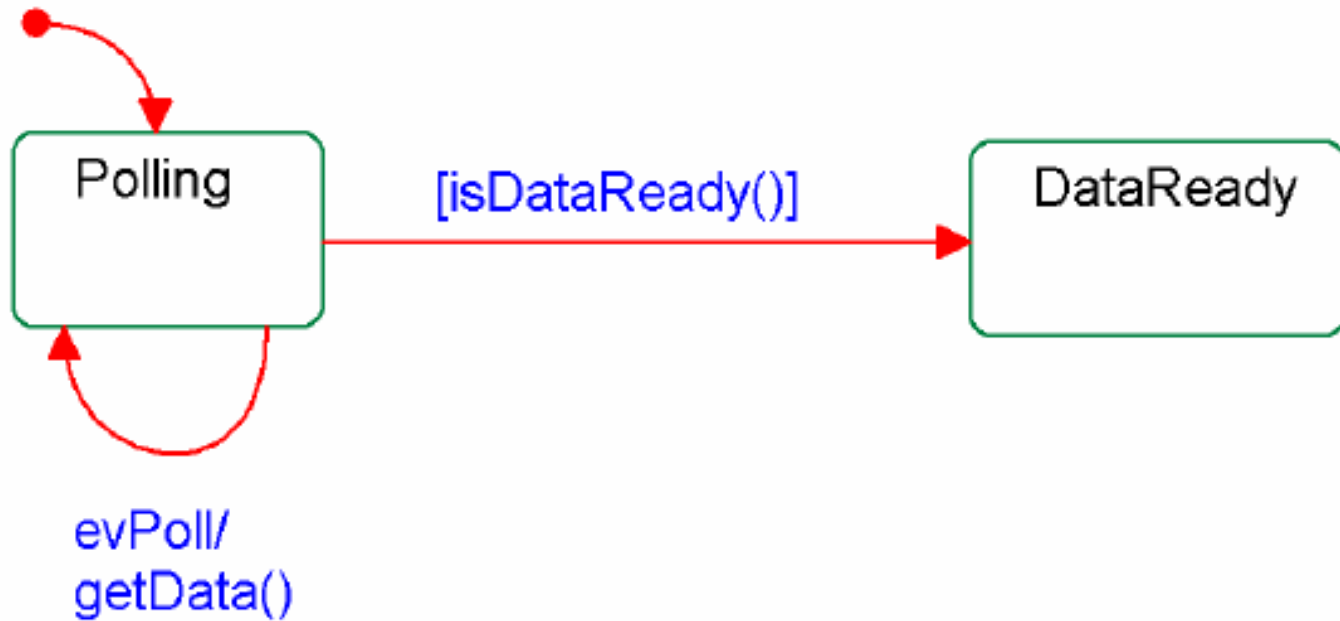
Transitions: Guards

- A **guard** is some condition that must be met for the transition to be taken
- Guards are evaluated prior to the execution of any action.
- Guards can be:
 - Variable range specification ex: [cost<50]
 - Concurrent state machine is in some state [IS_IN(fault)]
 - Some other constraint (preconditional invariant) must be met

Actions

- Actions are run to completion
 - Normally actions take a short period of time to perform
 - They may be interrupted by another thread execution, but that object will complete its action list before doing anything else
 - Actions are implemented via
 - An object's operations
 - Externally available functions
 - They may occur when
 - A transition is taken
 - A reaction occurs
 - A state is entered
 - A state is exited
-

Null-triggered Transitions

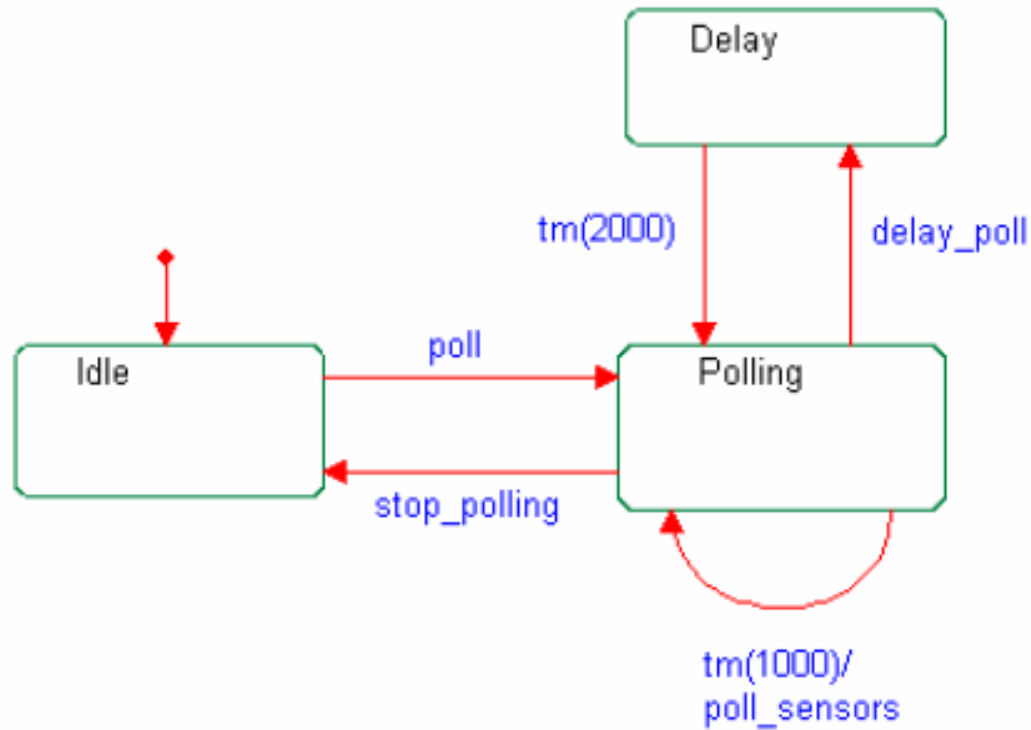


Timeouts

- When an object enters a state, any Timeout from that state are started
 - When a Timeout Expires, the State machine receives the expiration as an event
 - When an object leaves a state, any timeout that was started on entry to that state are cancelled
 - Only one timeout can be used per state, nested states can be used if several timeouts are needed
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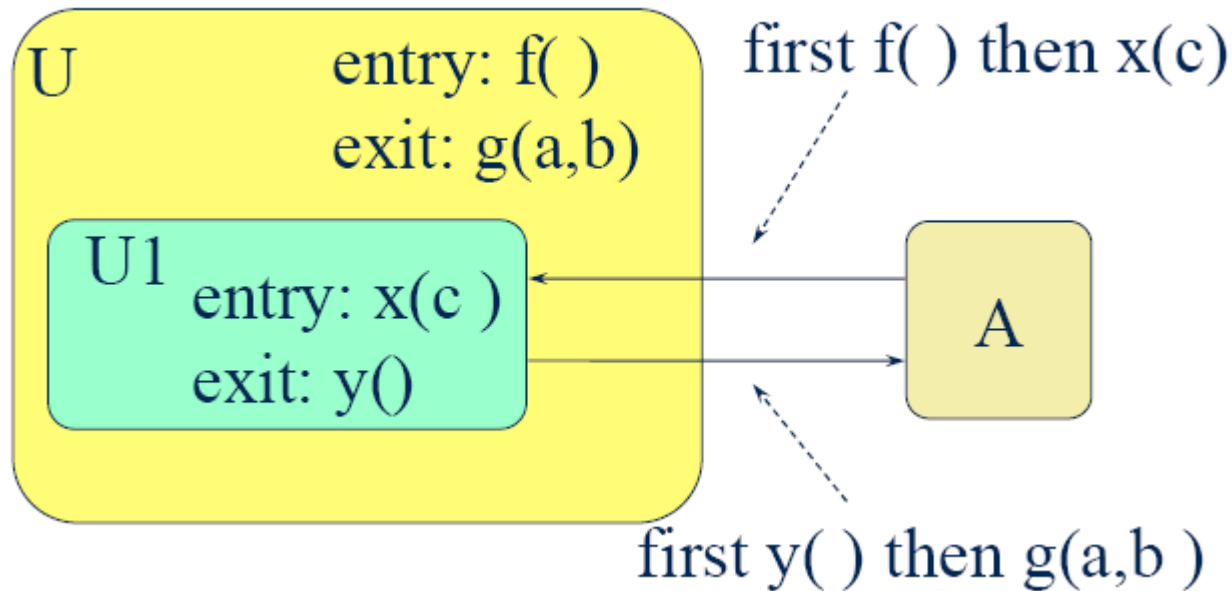
Timeouts

- Timeouts example:



Order of Nested States

- Execute from outermost – in on entry
- Execute from innermost – out on exit



Activity Diagrams

- An **Activity** is an ongoing non-atomic execution within a state machine.
 - An activity is interruptible.
- An **Activity Diagram** “shows the flow from activity to activity, addressing the dynamic view of a system.” [Booch et al. 1999]
 - An activity diagram is “a special case of a state machine that used to model processes involving one or more classifiers (*).” [OMG-UML v1.4]
 - An activity diagram is used to model the flow of activities in a procedure.

(*) A model elements that describes behavior and structural features, e.g., class, use case, interface, etc.

Activity Diagrams (cont'd)

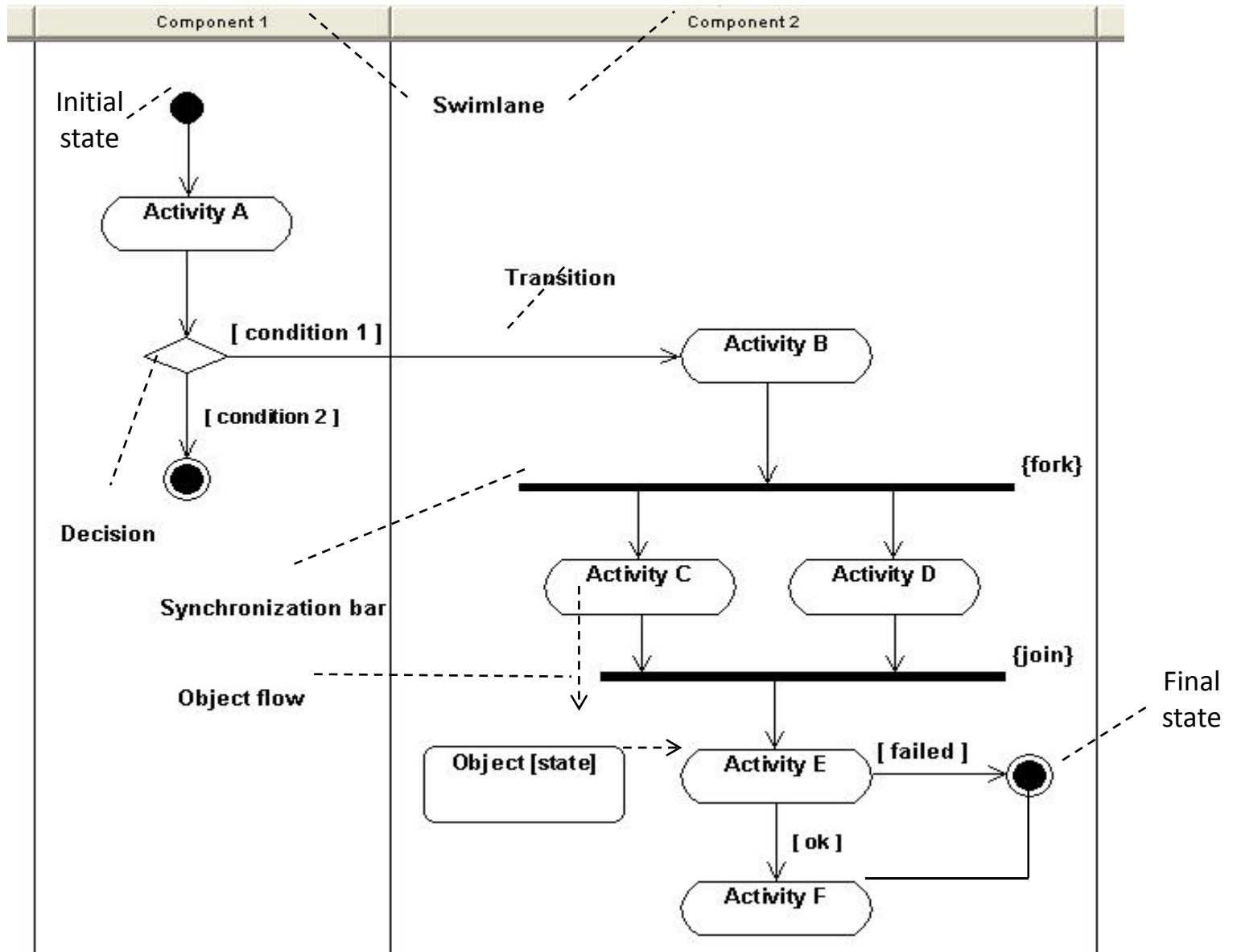
- An activity diagram consists of:
 - activity,
 - transition,
 - decision,
 - synchronization,
 - swimlanes,
 - initial state,
 - and final state.

Activity Diagrams

- Change in 2.0 to be based on token flow semantics
- Used when the primary means of transitioning from one state to another is upon completion of the previous activity not reception of an event
 - An activity diagram can be assigned to either a class, use case or an operation.
 - Useful for describing algorithms
- Each activity has a set of pins
 - Input pins bind input parameters to “local variables”
 - Output pins bind output parameters to “output variables”
 - An activity begins when input data appears on all input pins
 - When an activity completes, there is data on all the output pins
 - Activities are no longer triggered by events

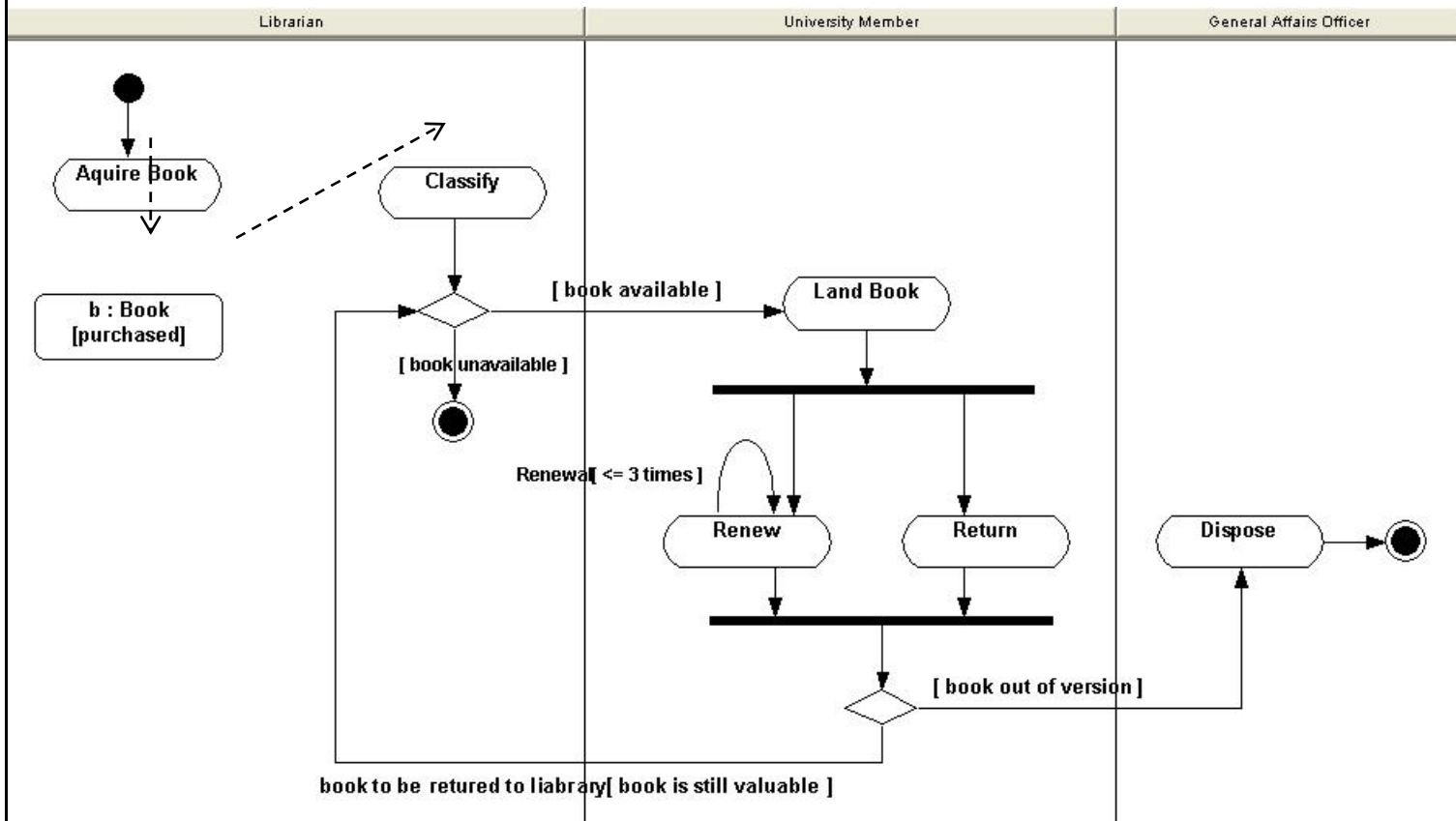
ACTIVITY DIAGRAMS (CONT'D)

- Activity diagram notations



ACTIVITY DIAGRAMS (CONT'D)

- Example: The life of a copy of book.



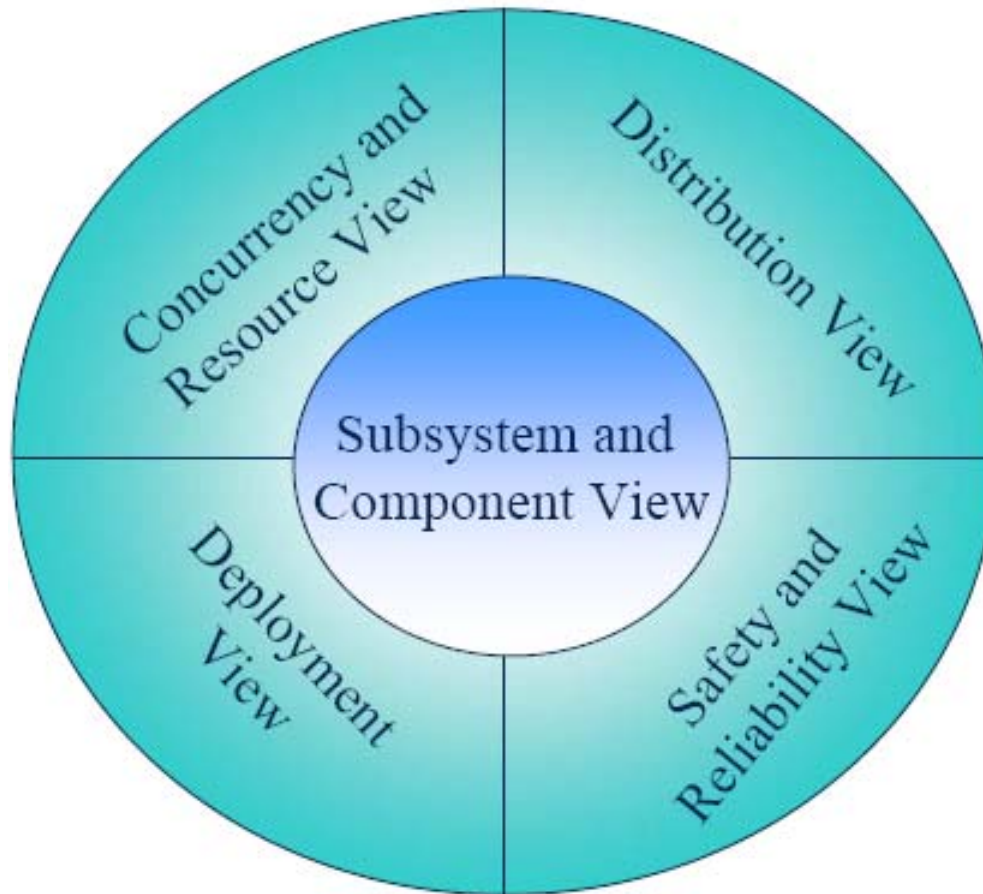
Activity Diagrams (cont'd)

- Activities and activity diagrams are associated either to:
 - a business process,
 - a class (a component),
 - an operation,
 - a use case (to describe the scenarios of a use case),

that is, you can use activity diagrams to describe these elements.

Architecture

Physical Architectural Views

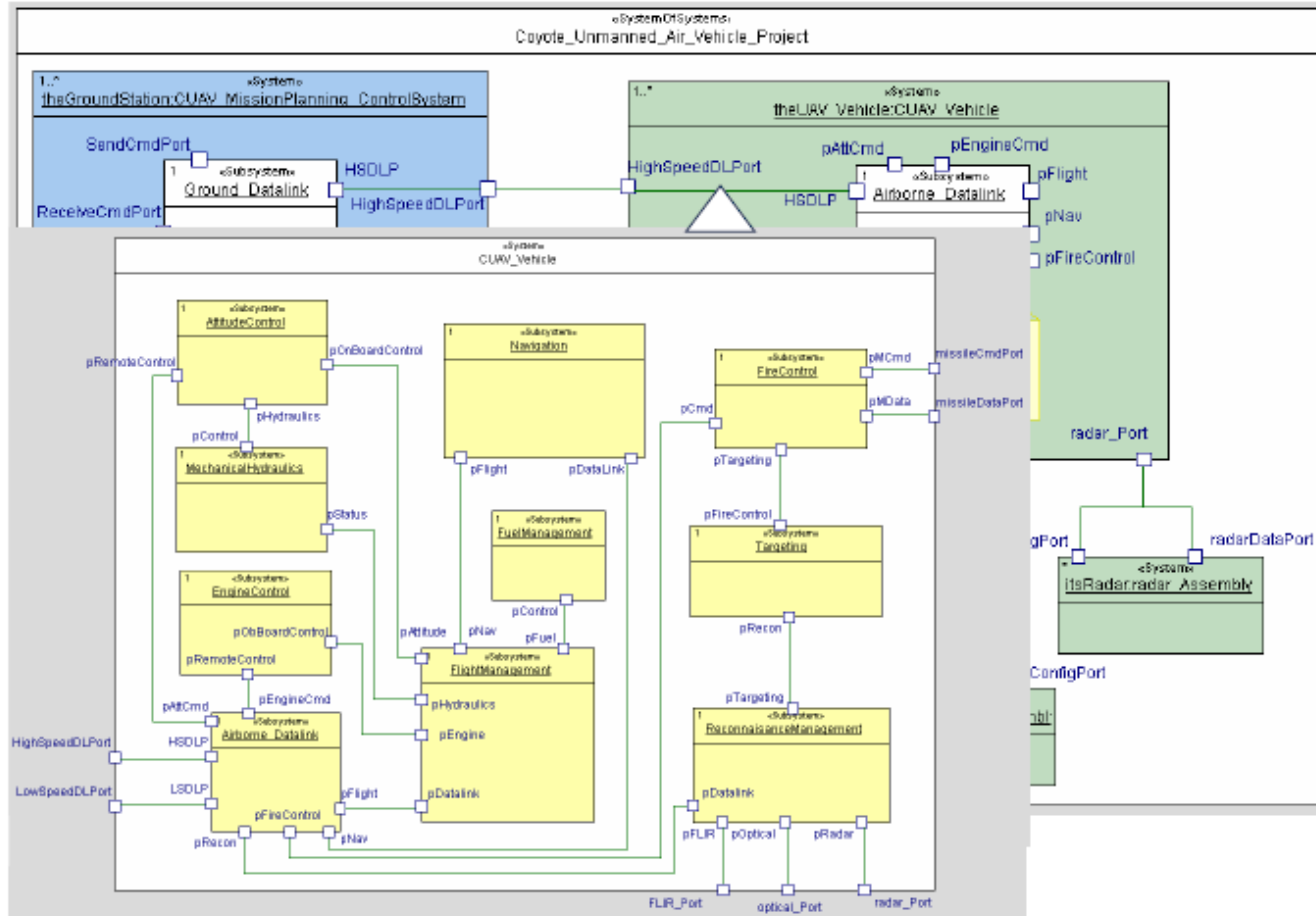


Physical Architectural Views

- Construct architectural design models
 - Subsystem Model
 - Concurrency Model
 - Distribution Model
 - Safety and Reliability Model
 - Deployment Model

 - Capture with
 - Class Diagrams
 - Package Diagrams
 - Component Diagrams
 - Deployment Diagrams
-

Subsystem Architecture



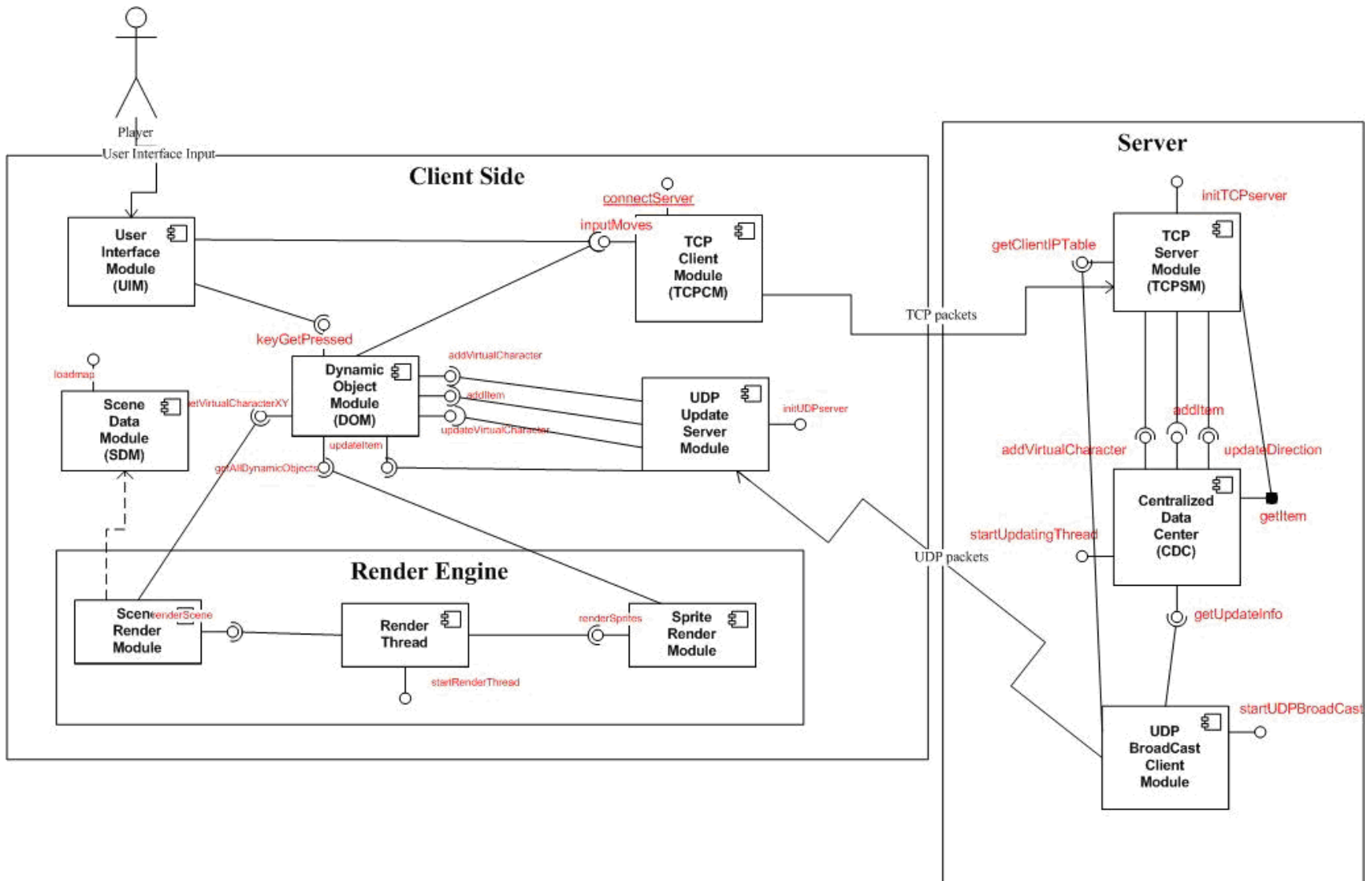
Subsystem and Component View

- A component
 - is the basic reusable element of software
 - organizes objects together into cohesive run-time units that are replaced together.
 - provides language-independent opaque interfaces
 - a metasubtype of (structured) Class
 - A subsystem
 - is a large object that provides opaque interfaces to its clients and achieves its functionality through delegation to objects that it owns internally
 - contains components and objects on the basis of common run-time functional purpose
 - a metasubtype of Component
-

Distribution Architecture

- Distribution model refers to
 - Policies for distribution objects among multiple processors and communication links, e.g.
 - Asymmetric distribution (dedicated links to objects with a priori known location)
 - Publish-Subscribe
 - CORBA and Broker symmetric distribution
 - Policies for managing communication links
 - Communication protocols
 - Communication quality of service management

Distribution Architecture

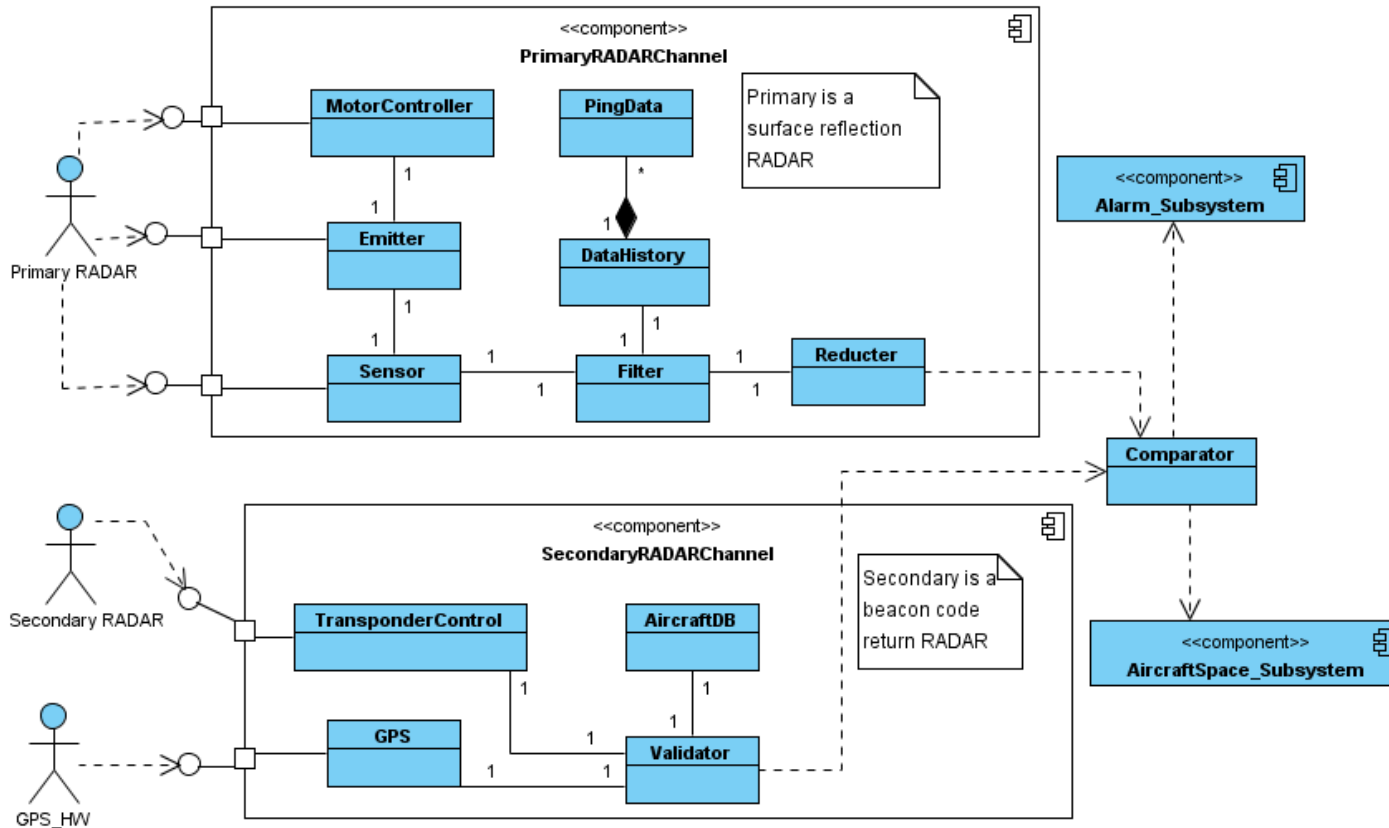


Safety and Reliability Model

- Safety and reliability model refers to the structures and policies in place to ensure
 - Safety
 - Freedom from accidents or losses (risk)
 - Reliability
 - High MTBF (Mean Time Between Failure)
 - Fault tolerance
- Safety and fault tolerance always require some level of redundancy

Safety and Reliability Architecture

Heterogeneous redundancy design

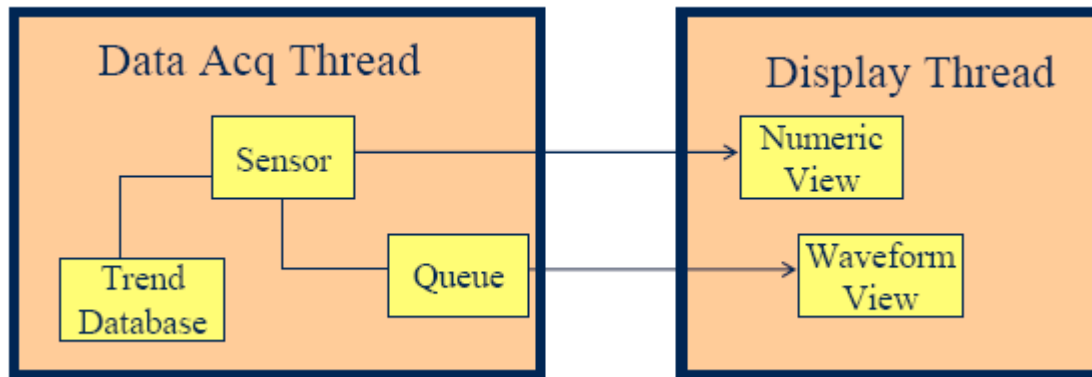


Concurrency Architecture

- Refers to
 - Identification of task **threads** and their properties
 - **Mapping** of passive classes to task threads
 - Identification of **synchronization policies**
 - **Task scheduling policies**
- Unit of concurrency in UML is the **«active»** object
 - «active» objects are added in architectural design to organize passive objects into threads
 - «active» objects contain passive semantic objects via composition and delegate asynchronous messages to them

Concurrency Model

- Active object is a stereotype of an object which owns the root of a thread
- Active objects normally aggregate passive objects via composition relations
- Standard icon is a class box with heavy line



Active Classes

- In UML 1.x the unit of concurrency was called the Active Object, shown with a thick border



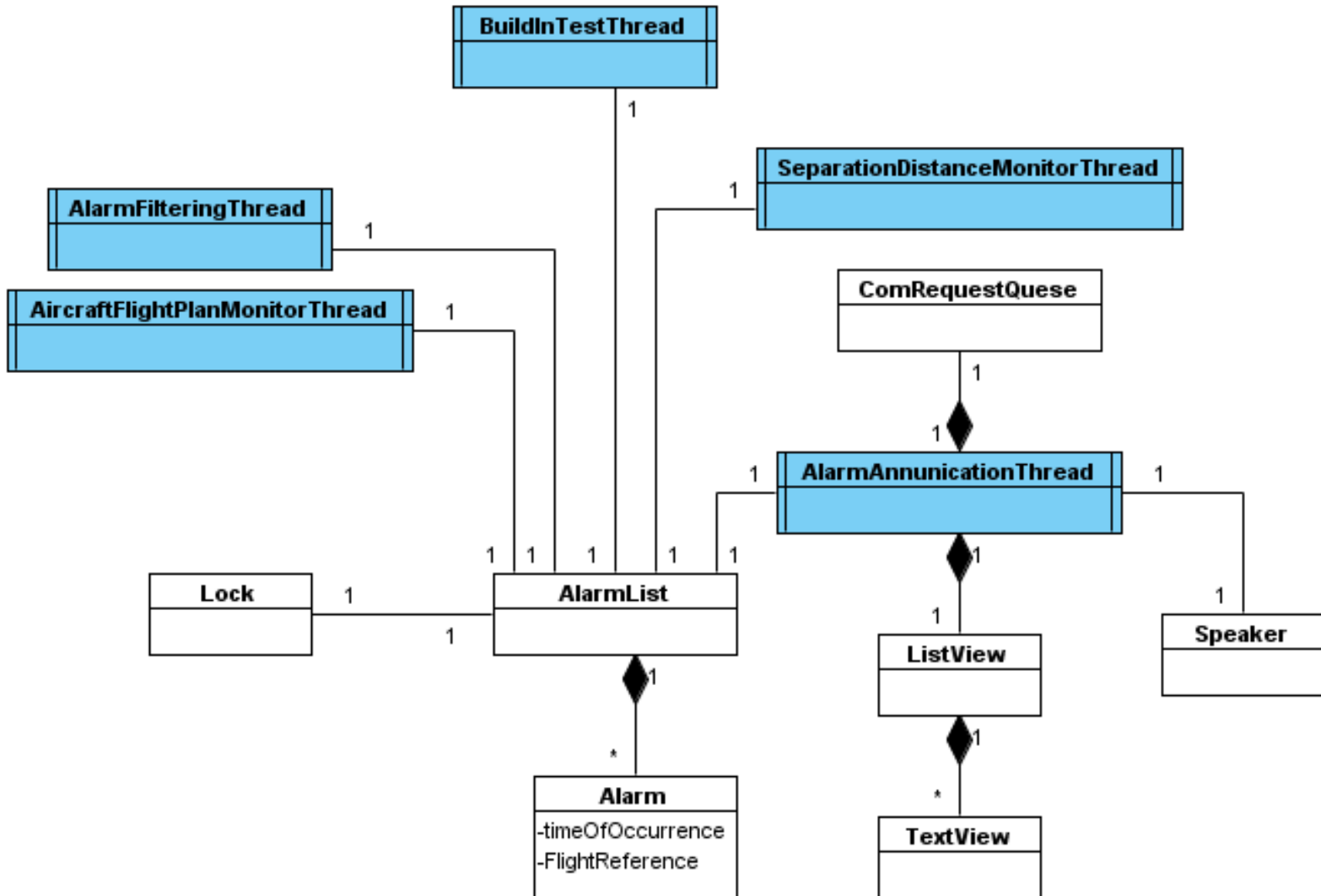
UML 1.x Active Object

- In UML 2.0 the notation has changed to double vertical lines, and is called an Active Class



UML 2.0 Active Class

Concurrency View

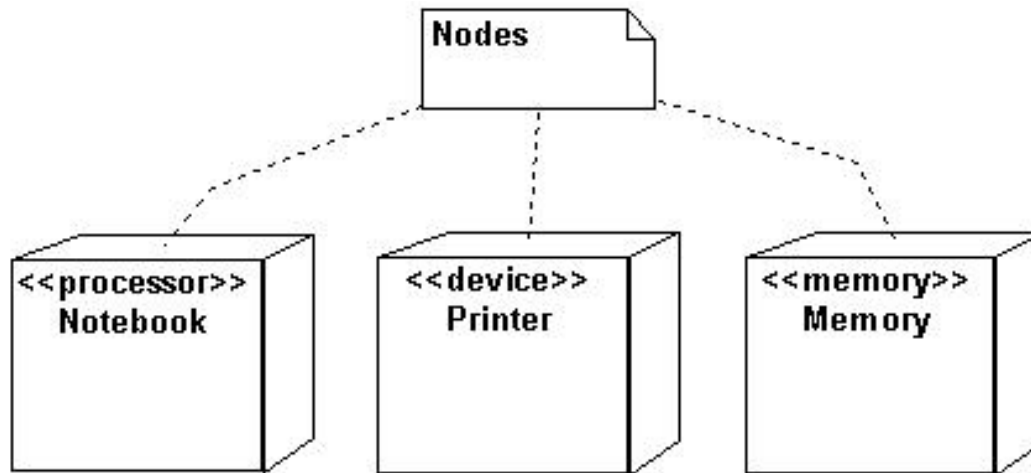


Deployment Architecture

- Maps software components and subsystems to hardware
 - Represents a device as a node
 - Iconic stereotypes are common
- Identifies physical connections among devices
 - May be buses, networks, serial lines, etc
 - Two primary strategies
 - Asymmetric
 - Design-time mapping of software elements to HW
 - Symmetric
 - Dynamic run-time mapping of software elements to HW

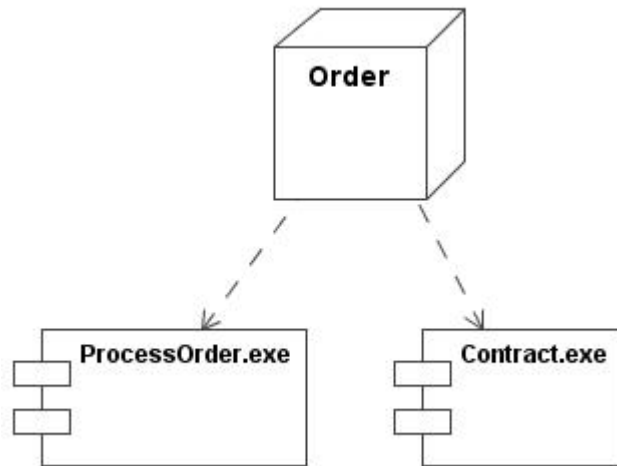
Deployment Diagrams

- A **Deployment Diagram** shows the configuration of runtime process nodes. It also addresses the static deployment view of a system.
- Representation of nodes.



Deployment Diagrams (cont'd)

- Examples:
 - Nodes and components.



- Connections.

